





European Research Conference: Buildings Europäische Forschungskonferenz: Gebäude

Fault Diagnosis and Adaptive Control of VAV Dampers in a Multizone Building



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Energy in TIME

- Energy IN TIME is a Large-scale integrating project within the 7th Framework Programme FP7-NMP, Subprogramme EeB.NMP.2013-4
- The main objective is to reduce the energy consumption and cost in the operational stage of buildings
- Development of an innovative simulation-based control technique with the overarching objective of automating the generation of optimal operational plans tailored to the actual building and users requirements

UL contribution

- Design of fault detection and diagnosis techniques (WP4)
- Design of adaptive control modules for fault at component and system level (WP3)





Issues and Objectives

Objectives

- Developments in fault detection and diagnosis algorithms for system and equipment level faults
- Reconfiguration of control strategies to adapt fault recovering the functionality of HVAC system and its demonstration on building simulator

Issues

- The mathematical modeling of overall building system
- The economic model predictive control optimization problem for large scale building
- Fault adaptive control through integration of fault detection and diagnosis algorithms with predictive control



Benchmark Building description





Building Model Development in SIMBAD

- SIMBAD →HVAC toolbox for the MATLAB/SIMULINK
- Flexibility in simulation with available weather data (for Nancy)
- Platform for application of different control strategies
 - Every zone contains:
 i) Temperature sensor

ii) VAV box

Air Handling Unit consists:
 i) Mixer
 ii) Heating Coil
 iii) Supply fan





Fault Detection and Diagnosis

- Dedicated bank of unknown input residual generators is designed based on the linearized thermal model of the building
- Disturbances are considered to be known
- Residuals are generated (residual : the difference between actual and computed signal)



- Each residual generator is driven by all outputs and all inputs except one input.
- **Residual** When all sensors are fault-free and fault occurs in i^{th} zone-actuator, residual follows isolation logic as $|r_i(k)| \ge Threshold_i$

 $r_i(k)$ represents the residual for i^{th} zone actuator



Simulation example





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When absolute value of residual is greater than threshold, the fault is detected and from the value of residual, diagnosis is followed.



Figure: Detection of damper stuck



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Fault Tolerant Control





f _{min}	0 kg/s	T _{samin}	20°C	y _{min}	19°C
f _{max}	0.4 kg/s	T _{samax}	40°C	y _{max}	25°C

Q and **R** are weights* Horizon is of one Day.

ref is desired temperature setpoints *u* is control input vector as $[f_{sai} \ T_{sa}(k)]^T$ *y* is output vector as $[\ T_{zi}(k)]^T$ *f_{min}* is minimum flow from VAV box *f_{max}* is maximum flow from VAV box *T_{samin}* is minimum supply air temperature AHU can provide. *T_{samax}* is maximum supply air temperature AHU can provide. *y_{min}* is lower temperature limit for comfort zone *y_{max}* is upper temperature limit for comfort zone

FTC Contd.



Figure: FDD and FTC structure

- FDD module detects and diagnose fault has occurred at zone-I where the stuck is at 52% allowing 0.21 kg/s fixed supply air flow.
- Online modification is done of the constraints on the decision variables under damper stuck failures occurrence.
- This information is updated in the MPC of the zone level temperature controller.
- Constraints are switched, which allows calculation of supply air temperature at fixed stuck supply air flow to maintain zone -1 temperature at 22°C



Simulation example- damper stuck case





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